

Intro. to Turbulence ()

Lecture 1, 2 : Navier-Stokes Eqs. / Turbulence

Lecture 3, 4 : Advection by Turbulence Velocities.

1. Fluid (Gas, Liquid)

Velocity Field, $u(t, x) \in \mathbb{R}^n$.



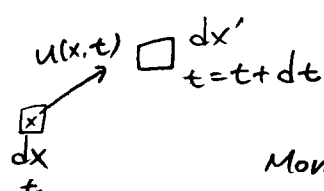
$\Omega \subset \mathbb{R}^n$, $n=2,3$

NSE

$$\begin{cases} \frac{\partial u}{\partial t} + u \cdot \nabla u = \nu \Delta u - \nabla p + f & \dots (0) \\ \nabla \cdot u = 0 & \dots (00) \end{cases} \quad u = (u_1, \dots, u_n)$$

ν : viscosity, p : pressure, f : external force.

"Physicist Derivation"



$$\begin{aligned} x' &= x + u(t, x) dt \\ dx' &= (1 + \nabla \cdot u dt) dx \end{aligned}$$

$$\text{Momentum} = \underbrace{\rho(t, x)}_{\text{density}} \underbrace{dx}_{\text{mass}} \cdot u(t, x)$$

$$\stackrel{t=t+dt}{=} \rho(t+dt, x') dx' u(t', x')$$

$$\text{Force} = \frac{d}{dt} \text{Momentum}$$

$$f_i = \frac{\partial}{\partial t} (\rho u_i) + \nabla \cdot (u_i \rho u) \dots (1)$$

$$\text{Mass} = \rho(t, x) dx$$

$$f + \nu \Delta u - \nabla p$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (u \rho) = 0 \dots (2)$$

Incompressible Fluid $\rho(x, t) = \text{const} = \rho_0$.

$$(2) \Rightarrow \nabla \cdot u = 0$$

$$(1) \Rightarrow (0) \text{ if } \rho_0 = 1$$

u, p : unknown

p can be computed from u .

$$\begin{aligned} \Omega &= (\mathbb{R}/2\pi L)^n \\ &\text{or } \mathbb{R}^n \end{aligned}$$

$$\nabla \cdot (0) \Rightarrow \nabla \cdot (u \cdot \nabla u) = -\Delta p + \nabla \cdot f$$

$$p = -\Delta^{-1} (\nabla \cdot (u \cdot \nabla u)) + \Delta^{-1} \nabla \cdot f$$

Δ^{-1} : Green Function in Ω

Define P on $\text{Vect}(\Omega)$

(2)

$$(Pu)_i(x) = u_i(x) - \partial_i (\Delta^{-1} \nabla \cdot u)(x)$$

$$\partial_i = \frac{\partial}{\partial x_i}$$

$P^2 = P$ projects on divergenceless vector fields.

$$\dot{u} + P(\nabla \cdot u) = \nu \Delta u + Pf$$

Integro. PDE. $\Delta^{-1} \propto \frac{1}{|x-y|} \quad n=3.$

p : non-local function.
instantaneous change on whole p .
→ makes NSE hard.

$$\partial_i Pu_i = \partial_i u_i - \underbrace{\Delta \Delta^{-1}}_{=1} \nabla \cdot u = 0.$$

$$\hat{u}(k) = \int_{\Omega} e^{ikx} u(x) dx.$$

$$\hat{P}u_i(k) = \left(\delta_{ij} - \frac{k_i k_j}{k^2} \right) \hat{u}_j(k).$$

$\hat{P}$ orthogonal in $L^2(\Omega)$.

2. $\exists!$ solutions.

$$\Omega = (\mathbb{R}/2\pi L)^d, \quad d=2,3$$

Energy $E(t) = \frac{1}{2} \|u(t)\|_2^2 = \int_{\Omega} e(t,x) dx, \quad e(t,x) = \frac{1}{2} u(t,x)^2$

Let u be a smooth solution of NSE.

$$\dot{e} = u \cdot \dot{u} = u \cdot (\nu \Delta u - u \cdot \nabla u - \nabla p + f)$$

check. $\nabla \cdot j = \nu (\nabla u)^2 + u \cdot f$ current $j = \frac{1}{2} (\nu \nabla - u) u^2 - u p$

$$\dot{E} = -\underbrace{\nu \int_{\Omega} (\nabla u)^2}_{\text{dissipation. due to viscosity}} + \underbrace{\int_{\Omega} u \cdot f}_{\text{pumping. (energy injection)}}$$

simplify: $\begin{cases} \int_{\Omega} u(0,x) dx = 0. \\ \int_{\Omega} f(t,x) dx = 0. \end{cases}$

HW Do general case!

$$\Rightarrow \int_{\Omega} u(t,x) dx = 0 \quad \forall t.$$

→ Poincaré $\| \nabla u \|_2^2 \geq C^{-1} \| u \|^2$

$$\dot{E} = -\nu \int_{\Omega} (\nabla u)^2 + \int u \cdot f \Rightarrow \frac{1}{2} \frac{d}{dt} \|u(t)\|_2^2 + \nu \|\nabla u\|_2^2 \leq \|u\|_2 \|f\|_2 \quad (3)$$

$$\Rightarrow \forall \varepsilon > 0 : \|u\|_2 \|f\|_2 \leq \frac{1}{2} \left(\varepsilon \|u\|^2 + \frac{1}{\varepsilon} \|f\|^2 \right)$$

$$\leq \frac{1}{2} \left(L^2 \varepsilon \|\nabla u\|^2 + \frac{1}{\varepsilon} \|f\|^2 \right)$$

$$\boxed{\varepsilon L^2 = \nu} \quad \frac{1}{2} \frac{d}{dt} \|u\|^2 + \underbrace{\frac{\nu}{2} \|\nabla u\|^2}_{\geq \frac{\nu}{2L^2} \|u\|^2} \leq \frac{L^2}{2\nu} \|f\|^2$$

$$\frac{d}{dt} \|u\|^2 + \frac{\nu}{L^2} \|u\|^2 \leq \frac{L^2}{\nu} \|f\|^2$$

$$\dot{y} + \alpha y \leq \beta \quad y(0) = y_0 \Rightarrow y(t) \leq e^{-\alpha t} y(0) + \frac{\beta}{\alpha} (1 - e^{-\alpha t}) \quad \text{Gronwall}$$

$$E(t) \leq e^{-\frac{\nu}{L^2} t} E(0) + \frac{L^4}{\nu} (1 - e^{-\frac{\nu}{L^2} t}) \cdot \sup_{s \leq t} \|f(s)\|_2^2$$

Weak Solutions

Let u be a smooth NS sol., v smooth s.t. $v(t, x) = 0 \quad \forall t > \frac{2}{\nu} T$

$$0 = \int_{\Omega \times [0, \infty)} v \cdot \overset{\text{NSE}}{\nabla \cdot (u \otimes u)} dt dx = - \int u (\dot{v} + \nu \Delta v + u \cdot \nabla v + f v) - \int p \nabla \cdot v \dots (*)$$

$$(00) \Rightarrow 0 = \int \phi \nabla \cdot u = - \int u \cdot \nabla \phi \dots (**)$$

$u(t) \in L^2(\Omega)$ is a weak solution to N.S. if $(*)$, $(**)$ holds $\forall v, \phi$

Leray '30s: $\exists$ weak solutions.

proof). Energy conservation + compactness.

Uniqueness & Smoothness of weak solns = \$1,000,000

$\boxed{n=3}$

$\boxed{n=2}$ (Easy) $\therefore$ Vorticity conservation. $\omega = \nabla \times u = \partial_1 u_2 - \partial_2 u_1$

$$NS \Rightarrow \dot{\omega} + u \cdot \nabla \omega = \nu \Delta \omega + g, \quad g = \partial_1 f_2 - \partial_2 f_1$$

"Advection / Transport E_3 "

$$\nabla \cdot u = 0 \Rightarrow u = \nabla^\perp \Delta^{-1} \omega, \quad \nabla^\perp = (\partial_2, -\partial_1)$$

Enstrophy = $\Phi(t) = \frac{1}{2} \|\omega(t)\|_2^2 = \int_{\Omega} \varphi(t, x) dx$ $\varphi(t, x) = \omega(t, x)^2$ ④

$$\dot{\varphi} = -\nu (\nabla \omega)^2 + \omega g + \nabla \cdot j\omega \quad , \quad j\omega = \frac{1}{2} (\nu \nabla - u) \omega^2$$

$$\Phi = -\nu \int_{\Omega} (\nabla \omega)^2 + \int_{\Omega} \omega g$$

$$\|\omega(t)\|_2^2 \leq C^{-\alpha t} \|\omega(0)\|_2^2 + \frac{1}{\alpha^2} (1 - e^{-\alpha t}) \sup_{s \leq t} \|g(s)\|_2^2 \quad , \quad \alpha = \frac{\nu}{L^2}$$

HW $\int_{\Omega} (\nabla u)^2 = \int_{\Omega} (\partial_i u_j)^2 = \int_{\Omega} \omega^2 \Rightarrow u \in H^1 \Rightarrow \exists 1 \text{ sol.}$

n=3 $\dot{\omega} = \nu \Delta \omega + [\omega, u] + g$

$$[\omega, u] = \underbrace{\omega \cdot \nabla u}_{\text{vorticity stretching}} - \underbrace{u \cdot \nabla \omega}_{\text{transport}}$$

Let $u(0, x) \in H^1$, then $u(t, x) \in H^1$ for $t \leq T(\|\nabla u\|_2^2)$

$T \rightarrow \infty$ as $\|\nabla u(0)\|_2^2 \rightarrow \infty$ keyhole's number

Turbulence Problem

There are 3 dim'l parameters.

Force of fixed spatial scale

L m

$L' = L/\ell$

v m/s.

$v' = \frac{\tau}{\ell} v$

ν m²/s.

$\nu' = \frac{\tau}{\ell^2} \nu$

length time

NS is scale covariant: pick ℓ, τ

~~$u(\lambda, t) = \frac{\ell}{\lambda} u(\frac{t}{\lambda^2}, \frac{x}{\lambda})$~~ $u(t, x) = \frac{\ell}{\tau} u'(\frac{t}{\tau}, \frac{x}{\ell})$

$f(t, x) = \frac{\ell}{\tau^2} f'(\frac{t}{\tau}, \frac{x}{\ell}) \quad \nu = \frac{\ell^2}{\tau} \nu'$

NS (u', f', ν') holds.

Reynold's number $R = \frac{Lv}{\nu} = R'$

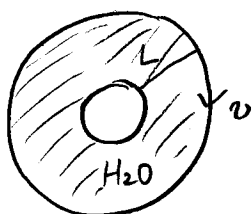
observations:

$R < O(1)$ Regular Flow $\Rightarrow \bigcirc \Rightarrow$

$R \in [O(1), O(10^4)]$ Transition to Chaos



$R > O(10^3)$ Turbulence



Experimental Facts: For large R .

Universality

Suppose $\exists$ sol. to NS $\forall u_0 \in L^2(\Omega)$.

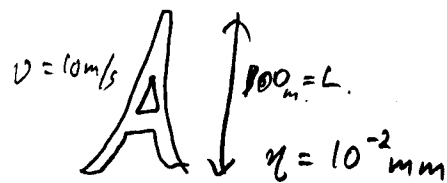
Let $\varphi_t: M \rightarrow M$ Flow of NS.

$$\varphi_t u_0 = u(t).$$

$F: M \rightarrow \mathbb{R}$ "observable."

eg. $F(u) = \prod_{j=1}^N u_{i_j}(x_j) \dots (*)$

Time average of F : $\langle F \rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T dt F(\varphi_t u_0)$



Facts. 1. $\langle F \rangle = G_N(x_1, \dots, x_N)$, $|x_i - x_j| \ll L$.

$\Rightarrow G_N$ is translation inv. $G_2(x, y) = g(x - y)$

2. $\exists$ length scale

η "Kolmogorov Scale" s.t. $\frac{\eta}{L} \rightarrow 0$ as $R \rightarrow \infty$.

s.t. self-similarity holds for scales l . $\eta \ll l \ll L$

$$\langle f((u(x) - u(y))) \rangle \approx \langle f(\lambda^{-\alpha}(u(\lambda x) - u(\lambda y))) \rangle$$

if $\eta \ll |x - y|$, $\lambda |x - y| \ll L$.

Structure Function $S_n(x, y) = \langle [(u(x) - u(y)) \cdot \hat{n}]^n \rangle$ $\hat{n} = \frac{x - y}{|x - y|}$

$$\approx \lambda^{-\alpha n} S_n(\lambda x, \lambda y) \quad \alpha \approx 1/3.$$

$$\Rightarrow S_n(x, y) \approx |x - y|^{\alpha n}. \quad \alpha \approx 1/3.$$

$$\eta \ll |x - y| \ll L. \quad \eta/L \rightarrow 0 \text{ as } R \rightarrow \infty.$$

$$L: \text{fixed}, R \rightarrow \infty \Rightarrow \eta \rightarrow 0.$$

$u(x)$ is only Hölder continuous w/
exponent $1/3$, $|u(x) - u(y)| \sim |x - y|^{1/3}$

eg. Brownian Motion $\beta(x) \in \mathbb{R}$, $x \in \mathbb{R}$.

$$\beta(x) - \beta(y) \approx \lambda^{-\alpha} (\beta(\lambda x) - \beta(\lambda y)), \quad \alpha = 1/2.$$

- Model of isotropic turbulence.

$$\begin{cases} \dot{u} = \nu \Delta u - u \cdot \nabla u - \nabla p + f \\ \nabla \cdot u = 0 \end{cases}$$

$f(t, x)$: • translation invariant in x, t .
• scale L .

f : Random. $f(t, x)$: ^{Gaussian} random variables, E = expectation value
 $E f(t, x) = 0$.
 $E f_i(t, x) f_j(s, y) = B_{ij}(x - y) \delta(t - s)$.

Scale L : $B(x - y) = C\left(\frac{x - y}{L}\right)$, C : smooth, decay at ∞ .

$\nabla \cdot u = 0$ $\Rightarrow \sum_i \partial_i B_{ij} = 0$

Aside on Brownian motion.

1. $\beta(t) \in \mathbb{R}$ is BM.

Gaussian random variable w/ $E \beta(t) = 0$, $E \beta(s) \beta(t) = \min(s, t)$
 $E \beta(t)^2 = t$, independent increments.

see Oksendal

$$E(\beta(t) - \beta(s))(\beta(s) - \beta(\tau)) = 0 \quad t > s > \tau$$

$$E(\beta(t) - \beta(s))^2 = t - s, \quad t > s.$$

$$\beta(t) - \beta(s) = \int_s^t d\beta(\tau)$$

$$E d\beta(\tau) d\beta(\tau') = \delta(\tau - \tau') d\tau d\tau'$$

$$d\beta(\tau) = \dot{\beta}(\tau) d\tau$$

$$\dot{\beta}: \text{white noise}, \quad \dot{\beta}(\tau) \dot{\beta}(\tau') = \delta(\tau - \tau')$$

$$d\beta(t)^2 = dt.$$

2. $\beta(t) \in \mathbb{R}^N$. $E \beta_i(t) \beta_j(s) = C_{ij} \min(t, s)$, $C \geq 0$.

3. BM in a function space.

$$\beta(t, x), \quad x \in \Omega \subset \mathbb{R}^n.$$

$$E \beta(t, x) \beta(s, y) = C(x, y) \min(t, s).$$

Stochastic Diff. Egn.

(2)

ODE $t \rightarrow u(t) \in M$.

$f(t) \in \mathbb{R}, v(t) \in \text{Vect } M$.

$$\dot{u} = v(t, u) + f(t).$$

SDE. $du = v(t, u)dt + d\beta(t)$.

$$u(t) = u(0) + \int_0^t v(t', u(t'))dt' + \int_0^t d\beta(t')$$

NS. $M = \text{Vect } \Omega$

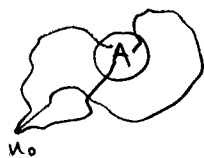
$$v(u, t, x) = v \Delta u(t, x) - u \cdot \nabla u - \nabla p, \quad \beta \text{ with } C(x, y) = C\left(\frac{x-y}{L}\right).$$

Solution of SDE is Markov process - whatever happens in the future depends on the past through present.

Transition Probabilities:

$$P_t(u_0, A) = \text{Prob}(u(t) \in A \mid u(0) = u_0).$$

= probability measure on M (on $L^2(\Omega)$)



$$\mu_t(A) = \int_M \mu_0(du_0) P_t(u_0, A)$$

μ_0 : probability measure on M .

Ergodicity

Stationary measure μ^* , $\mu_t = \mu_0 = \mu^* \quad \forall t$.

$$P_t(u_0, \cdot) \xrightarrow{t \rightarrow \infty} \mu^* \text{ a.e. } \mu_0.$$

[THM] $n=2$. For a "reasonable" C , including arbitrary big Re?
the NS SDE is ergodic $(B, \kappa), (E, \text{SINAI}), (KS)$

Properties of μ^*

• Notation: $u_0 \rightarrow u(t)$ depend on $\{\beta(s) \mid s \in [0, t]\}$.

$$E_{\{\beta(s) \mid s \leq t\}} F = \langle F \rangle_t.$$

$$E_{\mu^*} F = \int \mu^*(du) F(u) = \langle F \rangle = \lim_{t \rightarrow \infty} \langle F \rangle_t.$$

Energy Balance

Aside

Ito formula 1. $\beta(t) \in \mathbb{R}, du = v(u, t)dt + d\beta(t)$. $(d\beta)^2 = dt$.

$$F: M \rightarrow \mathbb{R}, F(u), dF = (vdt + d\beta) F'(u)$$

$$+ \frac{1}{2} \underbrace{d\beta^2(t)}_{dt} F''(u)$$

2. $\beta_1, \dots, \beta_N \in \mathbb{R}^N$

$$dF = (v_i dt + d\beta_i) \partial_i F + \frac{1}{2} C_{ij} \frac{\partial^2 F}{\partial u_i \partial u_j}, \quad d\beta_i d\beta_j = C_{ij} dt$$

$$3. \beta(t, x). \quad dF = \int_{\Omega} (v_i(t, x) dt + d\beta_i(t, x)) \frac{\delta F}{\delta u_i(x)} + \frac{1}{2} \iint_{\Omega \times \Omega} C_{ij} \left(\frac{x-y}{L} \right) \frac{\delta^2 F}{\delta u_i(x) \delta u_j(y)} \quad (3)$$

Ex. $F = \frac{1}{2} u(t, x)^2 = e(t, x)$

$$de = (-\nu (\nabla u)^2 dt + u \cdot d\beta + \nabla \cdot j dt) + \frac{1}{2} \text{Tr} C(\omega)$$

$$\langle de \rangle_t = \langle u d\beta \rangle = 0. \quad u(t) = \beta(s), \quad s \leq t.$$

$$\underline{u_0 = 0} \Rightarrow \langle \rangle_t \text{ is translation invariant.} \quad d\beta = \beta(t+\varepsilon) - \beta(t).$$

$$\langle j(x) \rangle_t : x\text{-independent.}$$

$$\langle \nabla \cdot j \rangle_t = 0.$$

$$\varepsilon = \frac{1}{2} \text{Tr} C(\omega) = \text{rate of injection of energy by } F \text{ to the system.}$$

$$\frac{d}{dt} \langle e(t, x) \rangle_t = -\nu \langle (\nabla u(t, x))^2 \rangle_t + \varepsilon$$

stationary state

$$\underbrace{\nu \langle (\nabla u(t, x))^2 \rangle}_{\text{dissipation}} = \underbrace{\varepsilon}_{\text{injection}} \leftarrow \text{Energy balance.}$$

Hopf equations

$$G_N(t, x) = \langle \prod_{i=1}^N u(t, x_i) \rangle_t$$

$$\begin{aligned} \text{(Ito)} \quad \dot{G}_N &= \sum_{i=1}^N \langle (-\nu \Delta_i u(t, x_i) - P(u \cdot \nabla u)(t, x_i)) \cdot \prod_{j \neq i} u(t, x_j) \rangle \\ &\quad + \frac{1}{2} \sum_{i \neq j} C \left(\frac{x_i - x_j}{L} \right) \langle \prod_{k \neq i, j} u(t, x_k) \rangle \\ &= -\nu \sum_{i=1}^N \Delta_i G_N + D G_{N+1} + \sum C \left(\frac{x_i - x_j}{L} \right) G_{N-2}(\hat{i}, \hat{j}) \end{aligned}$$

Prop. (Kolmogorov 4/5 - Law)

Under suitable smoothness assumptions, $n=3$.

$$\lim_{L \rightarrow \infty} \lim_{\nu \rightarrow 0} S_3(\Lambda) = -\frac{4}{5} \varepsilon \zeta.$$

$$\text{where } S_3(\Lambda) = \left\langle \left(\frac{x}{|x|} (u(x) - u(0)) \right)^3 \right\rangle \quad \zeta = |x|.$$

Idea $N=2$ Hopf equation.

G_3 in terms of G_2

symmetry allows to solve S_3

Step 1. (Hopf)₂

$$-2\nu \langle \nabla u(x) \nabla u(y) \rangle$$

(4)

$$\begin{aligned} \text{Tr } C\left(\frac{x-y}{L}\right) &= +\nu \langle \Delta_x + \Delta_y \rangle \langle u(x) \cdot u(y) \rangle \\ &+ \langle (u(x) \cdot \nabla_x) u(x) \cdot u(y) \rangle + \langle (u(y) \cdot \nabla_y) u(x) \cdot u(y) \rangle \\ &+ \langle \nabla p(x) \cdot u(y) \rangle + \langle \nabla p(y) \cdot u(x) \rangle \end{aligned}$$

Assume 1. $\nu > 0 \Rightarrow G_N(x)$ are smooth (& translation invariant)
2. $\lim_{\nu \rightarrow 0} \langle \nabla u(x) \nabla u(y) \rangle$ exists if $x \neq y$.

$$\text{(HW)} \quad \nabla \cdot u = 0 \Rightarrow \Delta = -\frac{1}{2} \nabla_x \cdot \langle \delta u (\delta u)^2 \rangle$$

$$\nu \langle \nabla u(x) \cdot \nabla u(y) \rangle - \frac{1}{4} \nabla_x \langle \delta u (\delta u)^2 \rangle = \frac{1}{2} \text{Tr } C\left(\frac{x-y}{L}\right)$$

1. $\nu > 0, x \rightarrow y. \quad \nu \langle (\nabla u(x))^2 \rangle = \varepsilon. \quad \text{Energy Balance}$

2. $x \neq y, y=0. \quad \nu \rightarrow 0 \quad -\frac{1}{4} \nabla \langle \delta u (\delta u)^2 \rangle = \frac{1}{2} \text{Tr } C\left(\frac{x-y}{L}\right) \rightarrow \text{redation (A,B,C)}$
 $= \varepsilon + o\left(\frac{x}{L}\right)$

$$S_3(r) = \langle (\hat{x} \cdot \delta u)^3 \rangle$$

$$b_{\alpha\beta,r}(x-y) = \langle u_\alpha(x) u_\beta(y) u_r(y) \rangle$$

$$\stackrel{\alpha\beta}{=} A(r) \delta_{\alpha\beta} \hat{x}_r + B(r) (\delta_{\alpha r} \hat{x}_\beta + \delta_{\beta r} \hat{x}_\alpha) + C(r) \hat{x}_\alpha \hat{x}_\beta \hat{x}_r$$

$$\rightarrow -6 \hat{x}_\alpha \hat{x}_\beta \hat{x}_r b_{\alpha\beta,r}(x) = -6C - 12B - 6A$$

2. $\partial_r b_{\alpha\beta,r} = 0$ & divergence...

$$-\left(\frac{2(A+B)}{r} + A'\right) \delta_{\alpha\beta} + \left(\frac{2(B+C)}{r} - C' - 2B'\right) \hat{x}_\alpha \hat{x}_\beta$$

$\Rightarrow$ 2 relations (A, B, C)

can be solved!

$$\rightarrow \underline{rC'' + 7C' + \frac{8}{r}C = \varepsilon + o\left(\frac{r}{L}\right)} \quad \text{regular at } r=0.$$

$$\Rightarrow C = -\frac{8}{15}r + o\left(\frac{r^2}{L}\right)$$

$$\lim_{L \rightarrow \infty} \lim_{\nu \rightarrow 0} S_3 = -\frac{4}{5}\varepsilon r + o\left(\frac{r^2}{L}\right)$$

Kolmogorov 41 theory.

$$C = C(x), \quad \nabla \cdot C = 0$$

(5)

$$\lim_{L \rightarrow \infty} \lim_{\nu \rightarrow 0} S_2(r, \nu, L, C) = -\frac{4}{5} \varepsilon r, \quad \varepsilon = \frac{1}{2} \text{Tr} C(0).$$

$$u'(t, x) = \frac{\tau}{L} u(\tau t, lx)$$

$$f'(t, x) = \frac{\tau^2}{L} f(\tau t, lx) \quad \frac{1}{\tau} \delta(t-s)$$

$$E f'(t, x) f'(s, y) = \frac{\tau^4}{L^2} C\left(\frac{L(x-y)}{L}\right) \delta(\tau t - \tau s)$$

$$u', f, \quad \text{NS:} \quad L' = L/\ell, \quad \nu' = \frac{\tau}{\ell^2} \nu, \quad C' = \frac{\tau^3}{\ell^2} C, \quad \varepsilon' = \frac{\tau^3}{\ell^2} \varepsilon.$$

$$S_n(r, \nu, L, C) = \langle (\hat{x} \cdot \delta u)^n \rangle_{\nu, L, C} \\ = \left(\frac{\ell}{\tau}\right)^n S_n\left(\frac{x}{\ell}, \frac{\tau}{\ell^2} \nu, \frac{L}{\ell}, \frac{\tau^3}{\ell^2} C\right)$$

[K4] $\exists \lim_{L \rightarrow \infty} \lim_{\nu \rightarrow 0} S_n(r, \nu, L, C)$ exists.

$$S_n(r, C) = \left(\frac{\ell}{\tau}\right)^n S_n\left(\frac{r}{\ell}, \frac{\tau^3}{\ell^2} C\right), \quad \ell = r, \quad \frac{\tau^3}{\ell^2} = \varepsilon^{-1}. \\ = (\varepsilon r)^{n/3} S_n\left(1, \left(\frac{C}{\varepsilon}\right)\right), \quad \frac{C}{\varepsilon} = \frac{C(x)}{\text{Tr} C(0)}. \\ \equiv A_n \quad \text{unit injection.}$$

$\nu \neq 0, L \neq \infty$

$$S_n(r, \nu, L, C) = (\varepsilon r)^{n/3} S_n\left(1, \left(\frac{\eta}{L}\right)^{4/3}, \frac{L}{2}, \varepsilon^{-1} C\right), \quad \eta = \varepsilon^{-1/3} L$$

Inertial range, $\eta \ll r \ll L$ dissipation injection Kolmogorov scale

$$R = \frac{L^{4/3} \varepsilon^{1/3}}{\nu} = \frac{L \nu}{\nu} \quad \eta = R^{-3/4} L \quad (R = 10^8)$$

$$S_n(r) \sim r^{f_n}, \quad f_n = n/3.$$

$$f_2 \approx 0.7, \quad f_3 = 1, \quad f_4 \approx 1.28, \quad f_7 \approx 2.0 \quad \text{gets worse.} \\ (0.66) \quad (1.33) \quad (2.33)$$

$S_n = \langle (\cdot)^n \rangle$, f_n : convex or concave in n . Hölder.

$$S_n(r, \nu, L, C) = (\varepsilon r)^{n/3} \left(\frac{L}{r}\right)^{\frac{n}{3} - f_n} \left(1 + O\left(\frac{r}{L}, \frac{\eta}{L}\right)\right)$$

$$\left(\frac{L}{r}\right)^{f_n - \frac{n}{3} \delta_2}$$

$$\left(\frac{r}{\eta}\right)^{f_n - n/3}$$

Calculate this #.

Intermittence. $S_n(r) / S_2(r)^{n/2}$

if $\hat{x} \cdot \delta u$ Gaussian $\Rightarrow$ CONSTANT